

Dynamic thermal models with the Filter-EWM-MBE (FEM) correction approach

...or linear regressions everywhere

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2023 European PVPMC Workshop, Mendrisio

Making equation-based models reliably dynamic

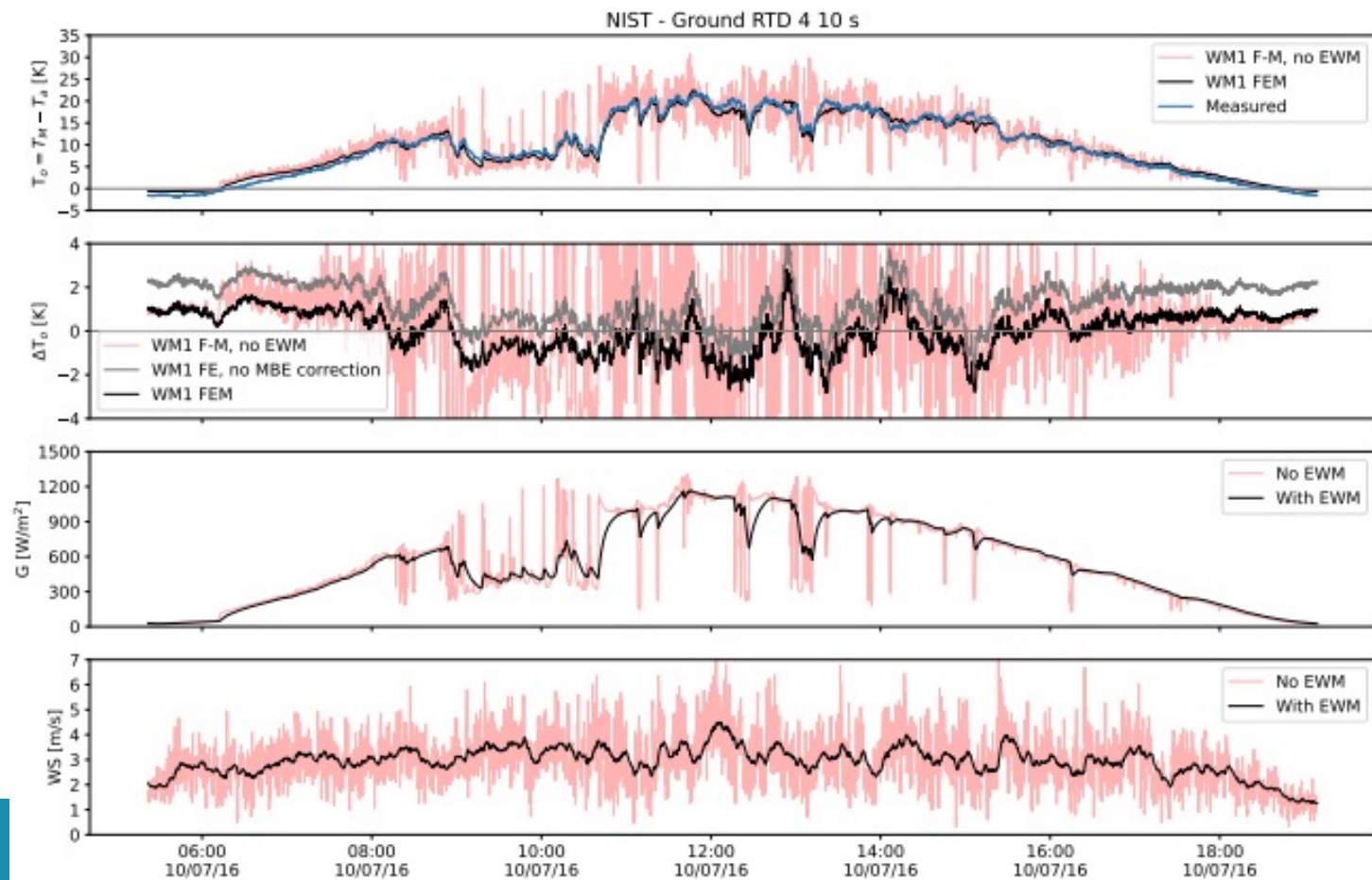
- After irradiance, temperature estimation is the most important factor
- Thermal models were (implicitly) steady-state \Rightarrow better RMSE, MAE, MBE for dynamic models
- Previous methods for dynamic models laborious or physics-intensive, e.g. Lobera et al, 2013: [10.1016/j.solener.2013.03.028](https://doi.org/10.1016/j.solener.2013.03.028)
- First step-change: Prilliman et al “[Transient Weighted Moving-Average Model of Photovoltaic Module Back-Surface Temperature](#)”, IEEE J PV, 2020 & pvlib implementation
 - Requires Finite Element Analysis (FEA) \Rightarrow labour intensive
 - Still too much physics!

Our solution: what if you can find what you need from measured data? \Rightarrow [Investigating methods to improve photovoltaic thermal models at minute-to-second timescales](#), Solar Energy, 2023

- Inspired by [Armstrong & Hurley](#) (A thermal model for photovoltaic panels under varying atmospheric conditions, Applied Thermal Engineering 2010) + [PhD](#) (2016) \Rightarrow Find τ from data
- Process for reliable coefficients: filters, linear regressions, corrections
- Tested on 15 sites, 24 datasets, from 1 s to 1 h

FEM in practice

- **Filter** step gives “ideal” coefficients.
 - 2 linear regressions instead of 1
(1 for irradiance, 1 for wind)
- **EWM** step maintains time resolution, and **smooths** output in the *right way*.
 - Python pandas (built-in), or custom numpy or cython
- **MBE_{train}** shifts output for $\text{MBE} \approx 0$
(and improves RMSE & MAE)



Filter-EWM-MBE (FEM) correction steps

- **Filter(s)**: to get steady-state model coefficients + thermal time constant τ
 - Ross/heating coefficient: low WS, variable G
 - WS convective cooling coefficient: high, constant G, variable WS
 - τ : how fast is ΔT , for given ΔG
- **Exponential weighted mean (EWM)**, using τ & time resolution Δt .
Makes model dynamic.
 - Smoothing coefficient α : $\alpha = 1 - e^{-\frac{\Delta t}{\tau}} \Rightarrow$ **link τ & Δt** \Rightarrow EWM adapts to different Δt
 - Apply in python pandas (or numpy, or...).
- **Mean Bias Error (MBE) correction**: use FE steps on training dataset, calculate **MBE_{train}**, use on testing or production dataset
 - Basically, don't stop at (first) MBE calculation; instead use as “free lunch” for improved RMSE, MAE and MBE.
- FEM is sequence of (mostly) independent steps: FE-, -EM, F-M, F-- all possible

Models & notation

Use only G , T_{amb} , $WS \Rightarrow$ wide implementation

- Over-temperature T_o :

$$T_o = T_M - T_{amb}$$

- Ross:

$$T_{o,Ross} = k \cdot G$$

- King or SAPM:

$$T_{o,King} = G \cdot e^{a+b \cdot WS}$$

- Faiman:

$$T_{o,Faiman} = \frac{G}{U_0 + U_1 \cdot WS}$$

- Wind model 1 (**WM1**):

$$T_{o,WM1} = k \cdot G \cdot e^{-WS/d}$$

- Wind model 2 (WM2):

$$T_{o,WM2} = G \cdot (k - h \cdot WS|_{WS \leq 8})$$

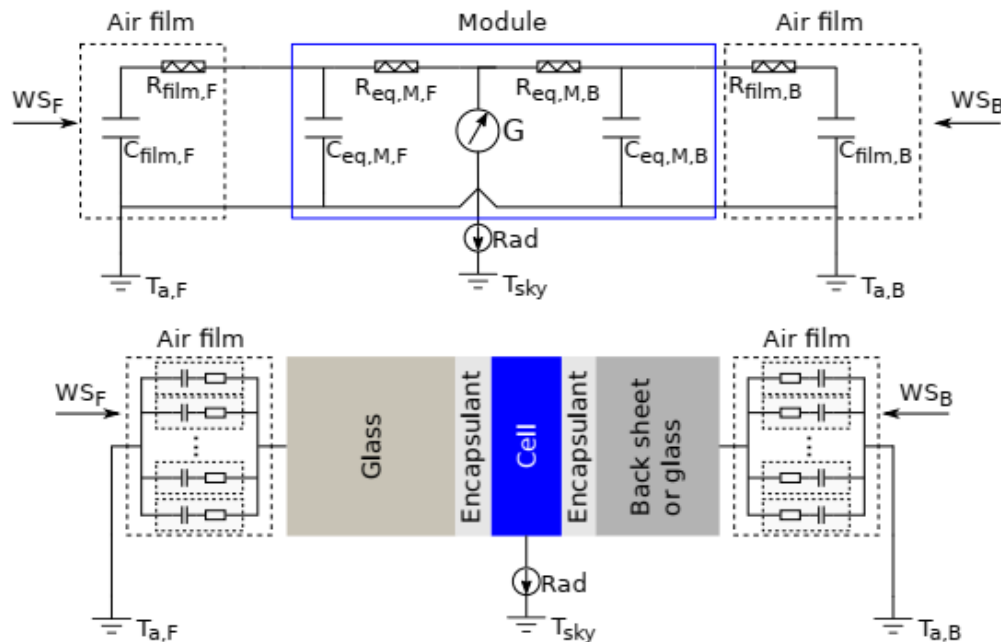
- Note: When $WS = 0$, (nearly) all models become Ross

- **$k = R\text{-value } r_{eq} [K/(W/m^2)] \Rightarrow$ easiest @ G_{STC} : $k = 30 \left[\frac{K}{1000 \frac{W}{m^2}} \right] \Rightarrow T_o = 30 K @ G_{STC}$**

- **$k = e^a = \frac{1}{U_0} \Rightarrow$ model bridge Ross – King/WM1/WM2/Faiman**

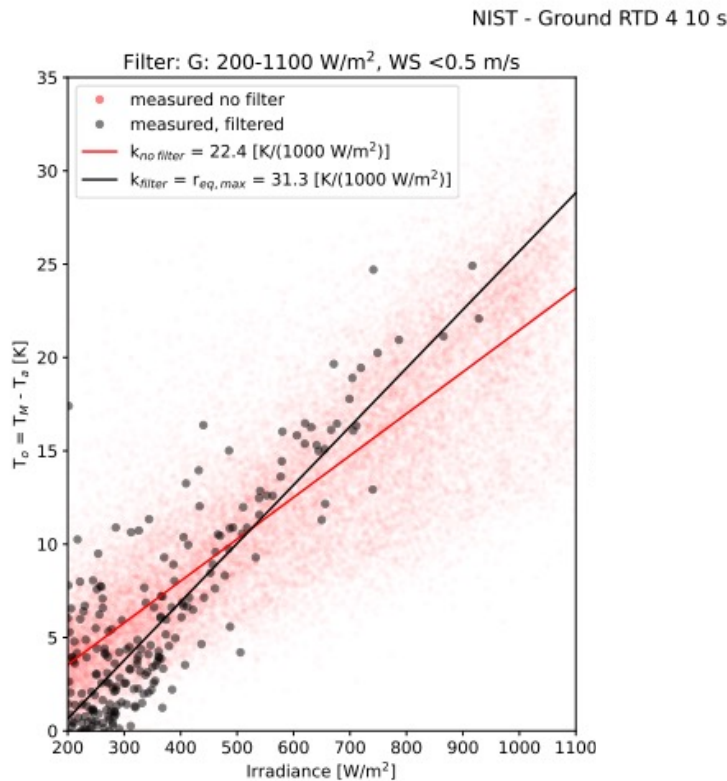
- King/SAPM = WM1 when using same coefficients.

Modified RC-equivalent network



- Air films: *series* RC-networks, in *parallel* to each other, impacted by WS.
 - Low WS: high r_{eq} , low(er) c_{eq}
 - High WS: lower r_{eq} , higher(er) c_{eq}
 - Explanatory link theory-data
- RC network \Rightarrow **thermal time constant τ**
 - From material properties
 - From outdoor measured data: look for irradiance *step changes*
- τ used for Exponential Weighted Mean (EWM) calculation \Rightarrow make model dynamic

Filter: determining k & d for WM1



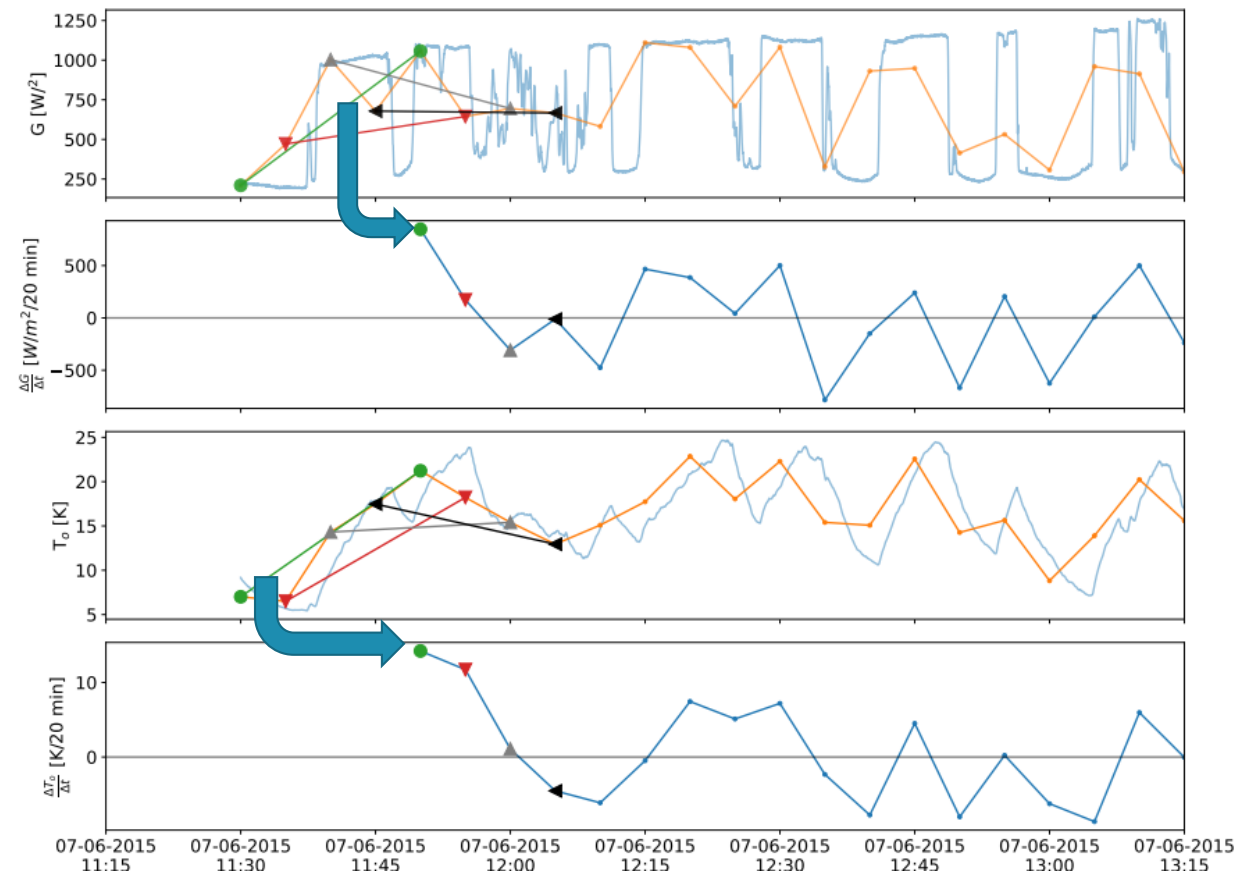
- To find k :
 - $\Delta t = 5$ min (resample data)
 - Filter: $G = 200-1100\ W/m^2$, $WS < 0.5\ m/s$
 - Linear regression T_o vs G
 - k gives T_o @ G_{STC} & $WS \approx 0\ m/s$.
- $$k = 31.3 \frac{mK}{W/m^2} \text{ gives } 31.3\ K \text{ above } T_{amb}$$
- $U_0 = \frac{1}{k} = \frac{1}{31.3/1000} = 31.9 \frac{W/m^2}{K}$

To find d :

- $\Delta t = 5$ min (resample data)
- Filter: $G = 1000 \pm 100\ W/m^2$, $WS = 0-8\ m/s$
- Linear regression $\ln(T_o/G)$ vs WS
- Faiman U_1 : G/T_o vs WS

Determining the thermal time constant τ from measured data

- Find $\frac{\Delta G}{\Delta t}$ & $\frac{\Delta T_o}{\Delta t}$ for 5 min data, and 4 periods (20 min total).
- 20 min: longest time window with sufficient frequency of sustained irradiance step changes
- Sort $\frac{\Delta G}{\Delta t}$ & $\frac{\Delta T_o}{\Delta t}$ by WS bins (0-1, 1-2, ..., 7-8 m/s).
- Linear regression of $\frac{\Delta T_o}{\Delta t}$ vs $\frac{\Delta G}{\Delta t}$ per WS bin \Rightarrow get τ



τ from measured data II

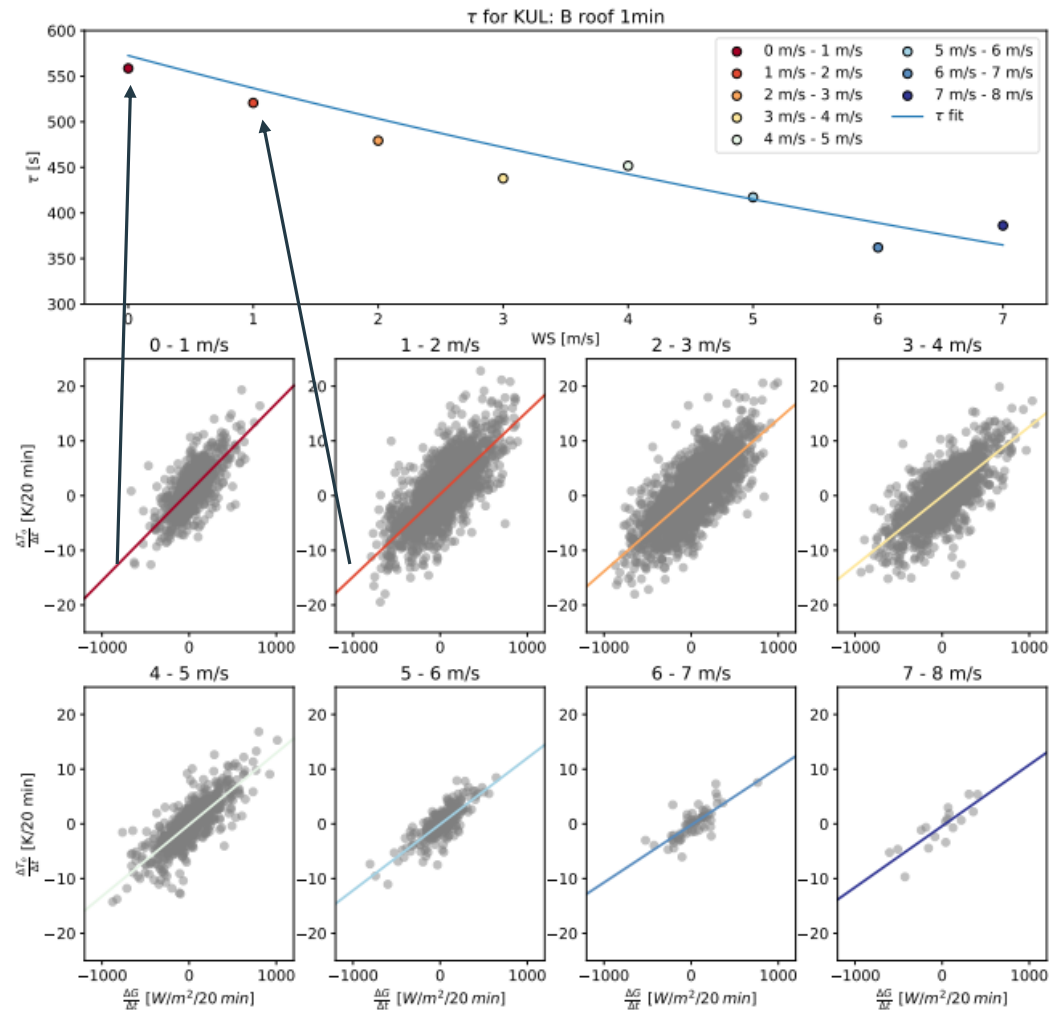
$$T_{o,WM1} = k \cdot G \cdot e^{-WS/d} \equiv r_{eq} \cdot G \cdot e^{-WS/d}$$

$$\begin{aligned} \tau(WS) &= \frac{\Delta T_o / \Delta t}{\Delta G / \Delta t} / r_{eq,max} \cdot \Delta t \\ &= \frac{r_{eq} \cdot (\Delta G \cdot e^{-WS/d}) / \Delta t}{\Delta G / \Delta t} / r_{eq,max} \cdot \Delta t \\ &= \frac{(\Delta G \cdot e^{-WS/d}) / \Delta t}{\Delta G / \Delta t} \cdot \underbrace{r_{eq}}_{\tau_0} \cdot \frac{\Delta t}{r_{eq,max}} \\ &= \tau_0 \cdot e^{-WS/d} \equiv \tau_0 \cdot e^{-WS/f} [s]. \end{aligned}$$

$$\tau_0 = \frac{r_{eq}}{r_{eq,max}} \cdot \Delta t, \text{ i.e. } \tau \text{ at } WS = 0 \text{ m/s}$$

Note: $f \geq d$ (smaller effect)

$$\text{e.g. } \Delta t = 20 \text{ min: } \tau_0 = \frac{16.96}{35.7} \cdot 1200 = 570 \text{ s (9.5 min)}$$



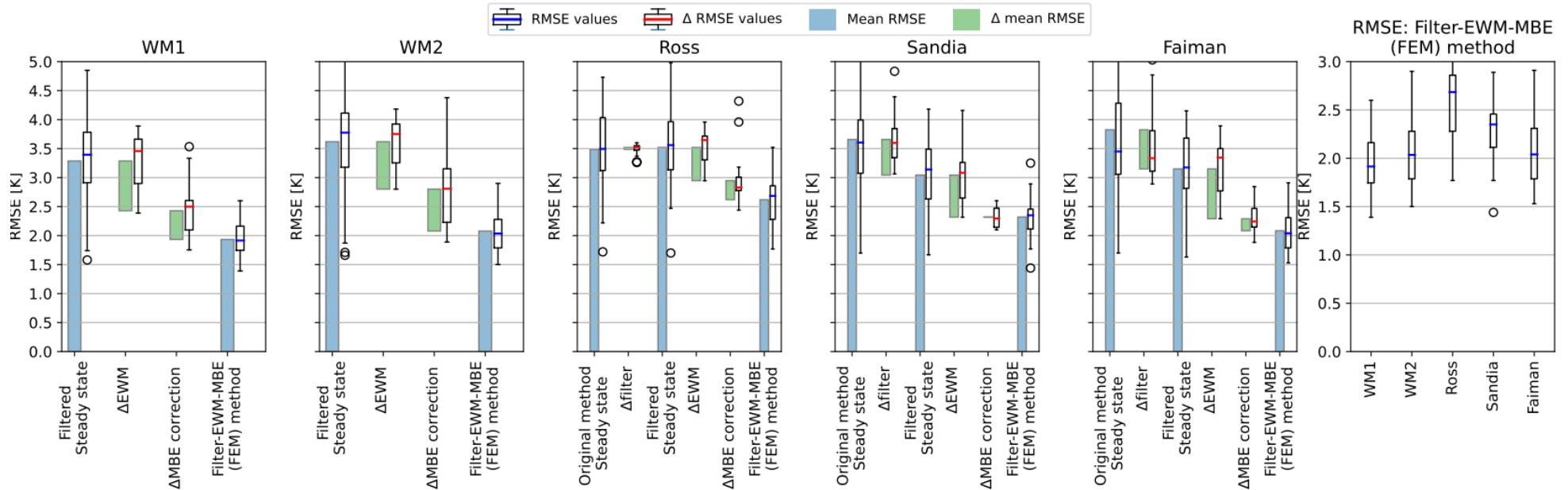
The EWM step

- $\tau = 6.3 \pm 1 \text{ min}$ ($378 \pm 60 \text{ s}$)
 - Works quite good for \sim all systems (design phase + evaluation after)
 - Better results possible from measured data
 - Impact on RMSE by choosing “wrong” ($\pm 60 \text{ s}$) τ is typ. $0.1 \text{ K} \sim 0.3 \text{ K}$ (e.g. 2.0 K w/ ideal τ , 2.3 K w/ non-ideal τ)
- Important: Δt and τ must have **same time units**: $\alpha = 1 - e^{-\Delta t/\tau}$
- EWM step in python pandas is *fast* ($<1 \text{ s}$ for 1 y @ 1 s modelling)
- `df['G'] \Rightarrow df['G'].ewm(alpha=alpha_EWM).mean()`

Impact of each step in FEM

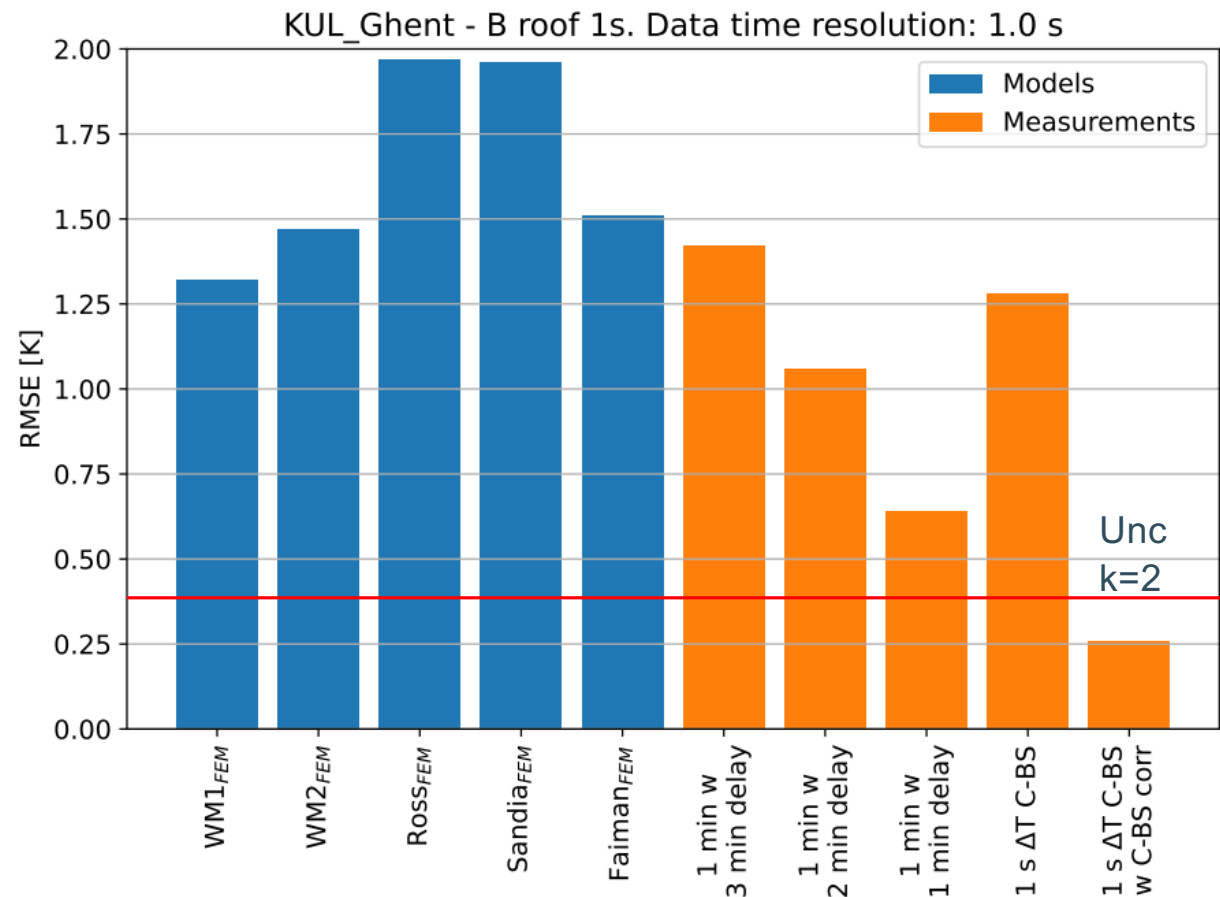
Impacts typically add (compounding effect): $F \Rightarrow FE \Rightarrow FEM$

Filter & EWM largest impact, MBE correction can be meaningful (~ 0.5 K RMSE)



Contextualisation

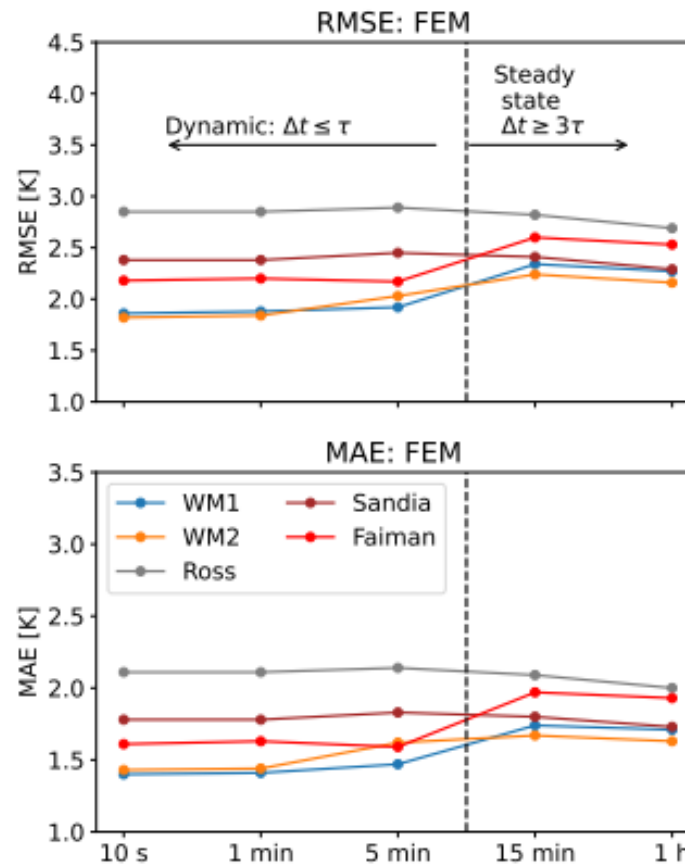
- Best model results \approx 1 min data w/ 3 min signal delay
- BS w/ BS-to-cell correction (with EWM) \approx identical to measured data (within meas. uncertainty)
- **Accurate and well-installed and well-maintained (backsheet) sensors still (way) better than models**



FEM with changing time resolution

FEM: better or constant KPIs as $\Delta t \rightarrow 0$

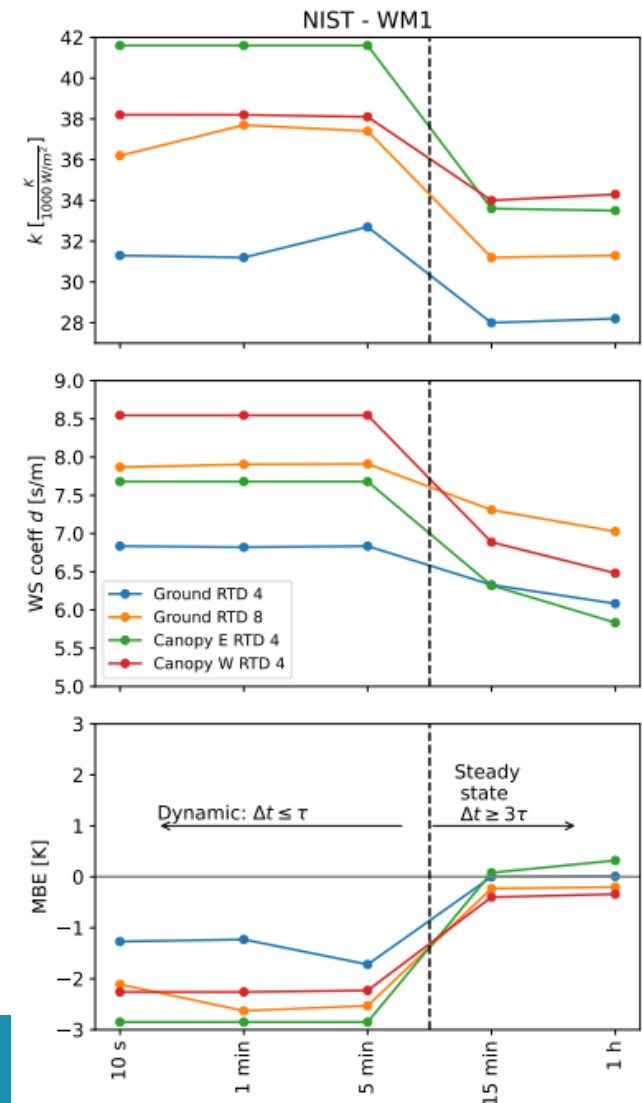
NIST - Ground RTD 4



Impact of time resolution

Difference between steady state & dynamic coefficient values can lead to important model errors

- Error: Use thermal model steady state coefficient values at dynamic time scales (e.g. PVsyst U_0 and U_1 , or WM1 k & d) erroneously for data analysis
 - E.g. PR calculation & weather correction, **using 5 min data and the contract model coefficients (@ 1 h).**
- $MBE_{\text{steady state, training}} \approx 0 \text{ K}$,
 $MBE_{\text{dynamic, training}} \approx -1 \text{ K to } -3 \text{ K}$
- As $\Delta t \rightarrow 1 \text{ s}$ k & d increase (or $k_{\text{dyn}} > k_{\text{steady state}}$)
- PR impact $\sim 0.5\%$ to 1.0% points ($\gamma = -0.35\%/K$).
 \Rightarrow EPC warranty envelope...



Conclusions

- FEM approach gives better, more stable (repeatable) coefficients \Rightarrow KPIs (RMSE, MAE, MBE) better or stable as Δt : $1\text{ h} \rightarrow 1\text{ s}$
- EWM step makes (any) model dynamic; fast, easy & simple use in python pandas
- Thermal time constant τ linked to material properties (τ_0), affected by mounting conditions (wind access)
- Module sensors (if accurate + well-installed + well-maintained) still much better than models
- Careful using coefficients: distinction between steady-state & dynamic needed
 - ~ **5-20% difference** for k & d (or U_0 & U_1) between steady state & dynamic \Rightarrow source of error when comparing design (PVsyst/pvlib/...) @ 1 h resolution with measured data at 1 s to 5 min

Thank you

- Many thanks to those who have shared their data:
 - NIST: <https://doi.org/10.18434/M3S67G>
 - IEA PVPS Task 13 PLR group: <https://doi.org/10.17605/OSF.IO/VTR2S>
 - University of Heidelberg: <https://doi.org/10.5281/zenodo.3958820>
 - KU Leuven: <https://doi.org/10.48804/RVTSD4>

Call to action: please share more data!

Contact: bert.herteleer@kuleuven.be

⇒ interest in evaluating FEM approach on 1-axis systems & different system types